

FW: ICARM 2020 Finalist for the Best Paper Award

Xuping Zhang <xuzh@mpe.au.dk>

Wed 16/12/2020 15.53

To: Farhad Farhadiyadkuri <ffyadkuri65@mpe.au.dk>

FYI

-----Original Message-----

From: IEEE ARM 2020 <icarm2020@gmail.com>

Sent: Friday, November 6, 2020 3:58 AM

To: Xuping Zhang <xuzh@eng.au.dk>

Subject: ICARM 2020 Finalist for the Best Paper Award

Dear Author(s),
Congratulations! Your paper

Paper ID: 95

Author(s): Farhad Farhadiyadkuri, Lars V. Strøm, Jesper B. Villadsen, Ole H. Hansen, Nicolai S. Sandborg, Mikkel L. Holm, and Xuping Zhang

Title: Control Strategy for a Developed Robotic Spine Exoskeleton

which was accepted by IEEE ICARM 2020, has been selected by the conference Award Committee as a finalist for the Best Paper

Award, which are Best Conference Paper Award, Toshio Fukuda Best Mechatronics Paper Award, Best Advanced Robotics Paper Award, and Best Student Paper Award.

Please confirm that one of the authors will attend and present the paper at the conference.

A finalist paper for the Best Student Paper Award must be presented by its first author.

Best wishes,

Qingquan Li
General Chair of IEEE ICARM 2020

Jianqiang Li
Program Chair of IEEE ICARM 2020

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Best,

Organizing Committee of IEEE ARM 2020